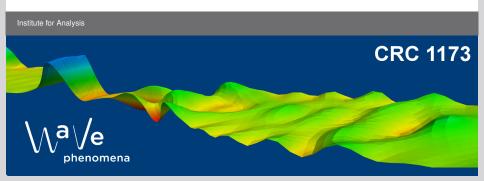


Time-periodic solutions of semilinear wave equations

Andreas Hirsch, Simon Kohler and Wolfgang Reichel

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Semilinear wave equations



Find time-periodic solutions $U: \mathbb{R}^{N+1} \times \mathbb{R} \to \mathbb{R}$ solving

(*)
$$w(x)U_{tt} - \Delta_{N+1}U = \Gamma(x)|U|^{p-1}U$$

traveling wave $U(x, x_{N+1}, t) = u(x, t - c^{-1}x_{N+1})$ with $x = (x_1, ..., x_N)$

$$(**) \qquad (\underbrace{w(x) - c^{-2}}_{=:V(x)})u_{tt} - \Delta_N u = \Gamma(x)|u|^{p-1}u$$

Properties of the profile *u*

- \blacksquare time-periodicity: u(x, t + T) = u(x, t)
- localization: $\lim_{|x|\to\infty} u(x,t)=0$

under suitable conditions on $V, \Gamma : \mathbb{R}^N \to \mathbb{R}$ and 1 . Typically <math>N = 1, 2.

Outline of the talk



- (A) motivation
- (B) our results
- (C) methods



1973 Ablowitz, Kaup, Newell, Segur: Sine-Gordon breather

$$u_{tt} - u_{xx} + \sin u = 0$$

$$u(x,t) = 4 \arctan\left(\frac{m\sin(\omega t)}{\omega\cosh(mx)}\right), m^2 + \omega^2 = 1$$



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1993 Denzler, 1994 Birnir, McKean, Weinstein: non-persistence

$$u_{tt} - u_{xx} + f(u) = 0,$$
 $f(0) = 0, f'(0) = 1$

has no breather-solution except for $f(u) = \sin u$.



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Why is it so delicate? Why is it so difficult?



Sine-Gordon equation: $Lu + \sin u = 0$ with $L = \partial_t^2 - \partial_x^2$ Try standard approach for the modified equation:

$$(\#) Lu + u = u^3$$

Ansatz
$$u(x,t) = \sum_{k \in \mathbb{Z}} u_k(x) e^{ik\omega t}, \quad u_k = u_{-k}$$

$$Lu(x,t) = \sum_{k \in \mathbb{Z}} (L_k u_k)(x) e^{ik\omega t}, \qquad L_k = -\frac{d^2}{dx^2} - k^2 \omega^2$$



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Then the nonlinear wave equation (#) becomes an infinitely coupled elliptic system

$$(\#\#) (L_k + 1)u_k = (\hat{u} * \hat{u} * \hat{u})_k$$

where $\hat{u} = (u_k)_{k \in \mathbb{Z}}$ and $(\hat{u} * \hat{u} * \hat{u})_k = \sum_{l,m \in \mathbb{Z}} u_{k-l} u_{l-m} u_m$.



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Note the difficulty arising from the spectrum

$$\sigma(L_k+1)=[-k^2\omega^2+1,\infty)$$



Idea: replace $L = \partial_t^2 - \partial_x^2$ by $L = V(x)\partial_t^2 - \partial_x^2$ and consider the modified equation

$$(\#) Lu + q(x)u = u^3$$

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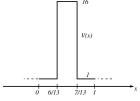
in particular if V(x), q(x) are periodic in x



2011 Comm.M.Phys.: Blank, Chirilus-Bruckner, Lescarret, Schneider

$$V(x)u_{tt} - u_{xx} + q(x)u = \pm u^3 \text{ in } \mathbb{R} \times \mathbb{R}$$

V 1-periodic,
$$q(x) = (q_0 - \epsilon^2)V(x), q_0 \approx 3.7703$$

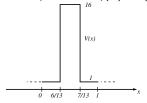




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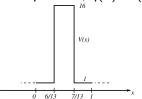
$$\exists$$
 small breathers for $0 < \epsilon < \epsilon_0$ $u(x,t) = O(\epsilon)$ $T = \frac{32}{13} = 2 \int_0^1 \sqrt{V(x)} \, dx$



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2019 Nonlinearity: A. Hirsch & W.R. Variational proof for large breathers

$$V(x)u_{tt} - u_{xx} = \pm |u|^{p-1}u$$
 on $\mathbb{R} \times \mathbb{R}$

(1)
$$V(x) = \alpha + \beta \delta^{per}(x), \beta > 32\alpha$$
,

$$1$$

$$(2) V(x) = \underbrace{\qquad \qquad }_{\beta}, 0 < \theta \ll \frac{1}{2}, \frac{\alpha}{\beta} = \frac{(1-\theta)^2}{\theta^2}$$

$$1$$

(3)
$$\exists$$
 suitable $V \in H^r_{per}(\mathbb{R})$ near $V_0 \equiv 1, r \in [1, 3/2), 1$



general understanding so far:

strong spatial structures allow for breathers



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In this talk: replace periodic structure by a waveguide structure

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where for $x = (x_1, ..., x_N)$ we have a cylindrically symmetric coefficient

$$W(x) = \begin{cases} W_0, & |x| < R, \\ W_1, & |x| > R. \end{cases} \quad 0 < W_1 < W_0.$$



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Traveling wave $U(x, x_{N+1}, t) = u(x, t - c^{-1}x_{N+1})$ leads to

$$(**) V(x)u_{tt} - \Delta_N u = \Gamma(x)|u|^{p-1}u$$

where

$$V(x) = \begin{cases} V_0 = W_0 - c^{-2} & |x| < R, \\ V_1 = W_1 - c^{-2} & |x| > R. \end{cases} \text{ choose } c \text{ s.t. } 0 < W_1 < c^{-2} < W_0.$$



$$(**) V(x)u_{tt} - \Delta_N u = \Gamma(x)|u|^{p-1}u$$

where

$$V(x) = \begin{cases} V_0 > 0 & |x| < R, \\ V_1 < 0 & |x| > R. \end{cases} \text{ write } V(x) = -\alpha + \beta \mathbf{1}_{B_R(0)} \text{ with } \beta > \alpha > 0.$$



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Note: (**) is elliptic outside $B_R(0)$, hyperbolic inside $B_R(0)$

9/17



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Theorem 1 (S. Kohler & W.R., part of PhD thesis)

For V as above, breathers with frequency $\omega=\frac{\pi}{2R\,\sqrt{\beta-\alpha}}$ exist in the following three cases:

(1)
$$n = 1, \Gamma > 0 \& \lim_{|x| \to \infty} \Gamma(x) = 0, 1$$

(2)
$$n = 2, \Gamma = \Gamma(r)$$
 bounded & $\Gamma > 0, 1 .$

(3)
$$n = 1$$
, $\Gamma = periodic$, bounded & inf $\Gamma > 0$, 1

(B) Comparison with the linear case in N=1



$$V(x)u_{tt}-u_{xx}=0$$

where

$$V(x) = \left\{ \begin{array}{ll} \beta - \alpha > 0, & |x| < R, \\ -\alpha < 0, & |x| > R. \end{array} \right.$$

With $u(x, t) = e^{ik\omega t}\phi(x)$ we get

$$L_k \phi = -\phi'' - k^2 \omega^2 V(x) \phi = 0$$
 on $\mathbb R$

⇒ exponential decay to 0 outside, oszillations inside the waveguide.

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In the nonlinear case: $\sqrt{\beta - \alpha}\omega R = \frac{\pi}{2}$ which is designed s.t. $0 \notin \sigma_p(L_k)$. However: $\sigma_{ess}(L_k) = [k^2\omega^2\alpha, \infty)$.

(B) Our results - extensions



(**)
$$V(x)u_{tt} - \Delta_N u = \Gamma(x)|u|^{p-1}u$$

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For $V = -\alpha + \beta 1_{B_R(0)}$ with $\beta > \alpha > 0$, breathers with $\omega = \frac{\pi}{2B\sqrt{\beta-\alpha}}$ exist if

- (1) n = 1, $\Gamma > 0$ & $\lim_{|x| \to \infty} \Gamma(x) = 0$, 1 .
- (2) n = 2, $\Gamma = \Gamma(r)$ bounded & $\Gamma > 0$, 1 .
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Generalizations for (1) and (2): rhs. in (**) = f(x, t, u)

- (H1) f continuous, $T = \frac{2\pi}{\omega}$ -periodic in t, $|f(x, t, s)| \le c(1 + |s|^p)$
- (H2) f(x,t,s) = o(s) as $s \to 0$ uniformly in $x,t \in \mathbb{R}$
- (H3) f(x,t,s) odd in $s \in \mathbb{R}$, $s \mapsto f(x,t,s)/|s| /\!\!/_s$ on $(-\infty,0)$ and $(0,\infty)$
- (H4) $\frac{F(x,t,s)}{s^2} \to \infty$ as $s \to \infty$ unif. in $x, t \in \mathbb{R}$, $F(x,t,s) := \int_0^s f(x,t,\sigma)d\sigma$

Inspired by Szulkin, Weth: The method of Nehari manifold, 2010.

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Generalizations for (3):

- (A1) $\Gamma = \Gamma_{\infty} + \tilde{\Gamma}$
- (A2) Γ_{∞} =periodic, bounded & inf $\Gamma_{\infty} > 0$
- (A3) $\lim_{|x|\to\infty} \tilde{\Gamma} = 0$, $\tilde{\Gamma} \ge -$ const. $e^{-\delta|x|}$ with $\delta > 2\sqrt{\alpha}\omega$.



$$(**) V(x)u_{tt} - \Delta_N u = \Gamma(x)|u|^{p-1}u$$

Ansatz

$$u(x,t) = (S\hat{u})(x,t) \sum_{k \in 2\mathbb{Z}+1} u_k(x) e^{\mathrm{i}k\omega t}, \quad u_k = u_{-k}, \quad \hat{u} = (u_k)_{k \in 2\mathbb{Z}+1}.$$



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Then the nonlinear wave equation (**) becomes an infinitely coupled elliptic system:

$$(***)$$
 $L_k u_k = (\Gamma(x)|u|^{p-1}u)_k$ with $L_k = -\Delta_N - k^2 \omega^2 V(x), \quad k \in 2\mathbb{Z} + 1$



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Note: $k \in 2\mathbb{Z} + 1 \Leftrightarrow u = \frac{T}{2}$ antiperiodic.

- avoids k = 0 problem with $0 \in \sigma(L_0)$
- compatible with nonlinearity



$$(***)$$
 $L_k u_k = (\Gamma(x)|u|^{p-1}u)_k$ with $L_k = -\Delta_N - k^2 \omega^2 V(x), \quad k \in 2\mathbb{Z} + 1$

Variational formulation:

$$J(\hat{u}) = \sum_{k \in 2\mathbb{Z}+1} \frac{1}{2} b_{L_k}(u_k, u_k) - \frac{1}{p+1} \int_{\mathbb{R}^N} \int_0^T \Gamma(x) |S\hat{u}|^{p+1} dt dx.$$

with

$$b_{L_k}(u_k, u_k) = \int_{\mathbb{R}^N} |\nabla u_k|^2 - k^2 \omega^2 V(x) u_k^2 dx$$

 $dom(b_{L_k}) = H^1(\mathbb{R}^N)$. But what is $dom(J) = \mathcal{H}$?



How to define dom(J)?

$$J(\hat{u}) = \sum_{k \in 2\mathbb{Z}+1} \frac{1}{2} b_{L_k}(u_k, u_k) - \frac{1}{p+1} \int_{\mathbb{R}^N} \int_0^T \Gamma(x) |S\hat{u}|^{p+1} dt dx.$$

June 9, 2021



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To get an idea: suppose $L_k = \gamma_k \text{ Id}$, i.e., γ_k is the eigenvalue of L_k . Then

$$\sum_{k \in 2\mathbb{Z}+1} b_{L_k}(u_k, u_k) = \sum_{k \in 2\mathbb{Z}+1} \gamma_k \|u_k\|_{L^2}^2$$

and

$$\mathcal{H} = \text{dom}(J) = \left\{ \hat{u} = (u_k)_{k \in 2\mathbb{Z}+1} : \sum_{k \in 2\mathbb{Z}+1} |\gamma_k| ||u_k||_{L^2}^2 < \infty \right\}$$

Analagously, we proceed if L_k is a self-adjoint operator ...



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Use functional calculus:

$$\begin{array}{lcl} L_k & = & \int_{\mathbb{R}} \lambda dP_{\lambda}^k = \int_{\sigma(L_k)} \lambda dP_{\lambda}^k \\ |L_k| & = & \int_{\mathbb{R}} |\lambda| dP_{\lambda}^k = \int_{\sigma(L_k)} |\lambda| dP_{\lambda}^k \end{array}$$

$$dom(b_{L_k}) = dom(b_{|L_k|}) = H^1(\mathbb{R}^N)$$

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If $0 \notin \sigma(L_k)$ then define projections

$$(\hat{u}^+)_k = \int_{0^-}^{\infty} 1 dP_{\lambda}^k(u_k), \quad (\hat{u}^-)_k = \int_{-\infty}^{0^+} 1 dP_{\lambda}^k(u_k)$$

so that $\mathcal{H}=\mathcal{H}^+\oplus\mathcal{H}^-$ and

$$\sum_{k \in 2\mathbb{Z}+1} b_{L_k}(u_k, u_k) = |||\hat{u}^+|||^2 - |||\hat{u}^-|||^2$$



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 \Rightarrow we can apply saddle point methods of J (e.g., generalized Nehari manifold method: Szulkin, Weth, The method of Nehari manifold, 2010.)



$$J(\hat{u}) = \sum_{k \in 2\mathbb{Z}+1} \frac{1}{2} b_{L_k}(u_k, u_k) - \frac{1}{p+1} \int_{\mathbb{R}^N} \int_0^T \Gamma(x) |S\hat{u}|^{p+1} dt dx.$$

- (i) choice of ω & ODE analysis $\Rightarrow (-c|k|, c|k|) \in \sigma(L_k)^c = \rho(k)$ for |k| > K.



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- (ii) for $|k| \le K$: 0 is at most an eigenvalue of finite multiplicity of L_k
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- (iV) by Riesz-Thorin interpolation & Fourier-transform we get that $S: \mathcal{H} \to L^{r+1}(\mathbb{R}^N \times [0, T])$ locally compact for $1 \le r < p^* = 1 + \frac{2}{N}$
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The proof strategy when we don't have compactness of P.S.-sequences:

dual variational method with q = 1/p:

$$Lu = \underbrace{\Gamma(x)|u|^{p-1}u}_{=:v(x)} \quad \Leftrightarrow \quad \Gamma(x)^{-q}|v|^{q-1}v = Kv \text{ with } K = L^{-1}$$

comparison with problem at infinity

$$L_{\infty}u = \Gamma(x)|u|^{p-1}u \quad \Leftrightarrow \quad \Gamma(x)^{-q}|v|^{q-1}v = K_{\infty}v \text{ with } K_{\infty} = L_{\infty}^{-1}$$

where

$$L = (-\alpha + \beta \mathbf{1}_{[-r,r]})\partial_t^2 - \partial_x^2, \qquad L_{\infty} = -\alpha \partial_t^2 - \partial_x^2 \text{ (elliptic)}$$



The proof strategy when we don't have compactness of P.S.-sequences:

• dual ground state level m, dual ground state level m_{∞} at infinity

$$m = \inf_{M} \int_{\mathbb{R}} \int_{0}^{T} \Gamma(x)^{-q} |v|^{q+1} dt dx,$$

$$M = \left\{ v \in L^{q+1}(\mathbb{R} \times [0, T]) : \int_{\mathbb{R}} \int_{0}^{T} v K v dt dx = 1 \right\},$$

$$m_{\infty} = \inf_{M_{\infty}} \int_{\mathbb{R}} \int_{0}^{T} \Gamma(x)^{-q} |v|^{q+1} dt dx,$$

$$M_{\infty} = \left\{ v \in L^{q+1}(\mathbb{R} \times [0, T]) : \int_{\mathbb{R}} \int_{0}^{T} v K_{\infty} v dt dx = 1 \right\}$$

- \blacksquare $m < m_{\infty} \Rightarrow m$ is attained
- $b_{K_{\infty}}(v_{\infty}, v_{\infty}) < b_{K}(v_{\infty}, v_{\infty}) \Rightarrow m < m_{\infty}$ for a d.g.s. v_{∞} of the problem at infinity



The proof strategy when we don't have compactness of P.S.-sequences:

Proof of $b_{K_{\infty}}(v_{\infty}, v_{\infty}) < b_{K}(v_{\infty}, v_{\infty})$:

- Take v_{∞} as the dual ground state and set $u_{\infty} = L_{\infty}^{-1}v$.
- u_{∞} solves $L_{\infty}u_{\infty} = \Gamma(x)|u_{\infty}|^{p-1}u_{\infty}$
- **a** asymptotic estimates for $l \in [0,3)$

$$\partial_t^I u_{\infty}(x,t) = U^I \cos(\omega t) e^{-\sqrt{\alpha}\omega |x|} + O(e^{-(\sqrt{\alpha}\omega + \epsilon)|x|})$$



The proof strategy when we don't have compactness of P.S.-sequences: For large n consider $v_{\infty}^{n}(x) = v_{\infty}(x-n)$ and set $\Psi^{n} = -L^{-1}(L-L_{\infty})u_{\infty}^{n}$. Then compute

$$b_K(v_{\infty}^n, v_{\infty}^n) - b_{K_{\infty}}(v_{\infty}^n, v_{\infty}^n) = \sum_k \int_{\mathbb{R}} L_k \psi_k^n \psi_k^n + \frac{1}{\beta k^2 \omega^2} L_k \psi_k L_k \psi_k \, dx$$



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since all eigenvalues of L_1 are positive.

Summary



Using

- saddle point methods, when P.S.-sequences are compact
- dual variational methods, when compactness does not hold
- spectral gaps of size O(|k|) around zero in the spectrum of L_k we find a variational setup for proving existence of time-periodic, spatially localited solutions of

$$(**) V(x)u_{tt} - \Delta_n u = \Gamma(x)|u|^{p-1}u$$

Theorem 1 (S. Kohler & W.R., part of PhD thesis)

For $V=-\alpha+\beta 1_{B_R(0)}$ with $\beta>\alpha>0$, breathers with $\omega=\frac{\pi}{2R\sqrt{\beta-\alpha}}$ exist if

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, $\Gamma > 0$ & $\lim_{|x| \to \infty} \Gamma(x) = 0$, $1 .$

(2)
$$n = 2, \Gamma = \Gamma(r)$$
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, $\Gamma = periodic$, bounded & inf $\Gamma > 0$, 1

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Thank you for your attention